Neighborhood Complexes and Rational Generating Functions

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Linear Programming: Given an $m \times d$ matrix A, an *m*-vector *b*, and a *d*-vector *c*,

minimize $c \cdot x$ such that $Ax \leq b$.



Simplex Algorithm:

- Start at a vertex of the polytope $\{x : Ax \leq b\}$.
- Step to new vertices until arrive at optimum.
- Allowable steps: along an edge of the polytope such that objective function decreases.



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Integer Programming:

minimize $c \cdot x$ such that $Ax \leq b$ and x is integral.



Question:

- Can we step between the feasible integer points and get to the optimum?
- What are the allowable steps?



The Frobenius Problem:

Let a_1, a_2, \ldots, a_n be nonnegative integers such that $gcd(a_1, a_2, \ldots, a_n) = 1$. Let

 $S = \{\lambda_1 a_1 + \cdots + \lambda_n a_n : \lambda_i \in \mathbb{N}\}.$

Question: What is the largest integer not in S?

Question: How many positive integers are not in S?

Example: $a_1 = 3$, $a_2 = 7$.

$$S = \{0, 3, 6, 7, 9, 10, 12, 13, 14, \ldots\}.$$

Question: What is the largest integer not in S? Answer: 11.

Question: How many positive integers are not in S? Answer: 6.

Given a set $S \subseteq \mathbb{N}$, define the generating function

$$f(S;t)=\sum_{a\in S}t^a.$$

In example,

$$f(S; t) = t^{0} + t^{3} + t^{6} + t^{7} + t^{9} + t^{10} + \cdots$$

We will shortly show

$$f(S;t) = \frac{1-t^{a_1a_2}}{(1-t^{a_1})(1-t^{a_2})}.$$

Let $T = \mathbb{N} \setminus S$ (which is $\{1, 2, 4, 5, 8, 11\}$ in the example).

$$f(T;t) = \frac{1}{1-t} - f(S;t)$$

= $\frac{(1-t^{a_1})(1-t^{a_2}) - (1-t)(1-t^{a_1a_2})}{(1-t)(1-t^{a_1})(1-t^{a_2})}$.

The largest integer not in S is the degree of the polynomial f(T; x), which is

$$(1 + a_1a_2) - (1 + a_1 + a_2) = a_1a_2 - a_1 - a_2.$$

The number of positive integers not in S is f(T; 1), which is (taking the limit as $t \rightarrow 1$)

$$\frac{a_1a_2-a_1-a_2+1}{2}$$

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Proof by Example: Frobenius Problem with $a_1 = 2$, $a_2 = 5$.

$$\frac{1}{(1-t^2)(1-t^5)} = (1+t^2+t^4+\cdots)(1+t^5+\cdots)$$
$$= 1+t^2+t^4+t^5+t^6+t^7+t^8+t^9+2t^{10}+\cdots$$

Proof by Example: Frobenius Problem with $a_1 = 2$, $a_2 = 5$.



Problem: These intervals may have more than one integer point.

Proof by Example: Frobenius Problem with $a_1 = 2$, $a_2 = 5$.



Let $Q = \{(x, y) : x \ge 5, y \ge 0\}.$

The points in Q give us:

$$\frac{t^{10}}{(1-t^2)(1-t^5)}.$$

Proof by Example: Frobenius Problem with $a_1 = 2$, $a_2 = 5$.



Each interval has only one integer point outside of Q:

$$f(S;t) = \frac{1}{(1-t^2)(1-t^5)} - \frac{t^{10}}{(1-t^2)(1-t^5)} \\ = \frac{1-t^{10}}{(1-t^2)(1-t^5)}.$$

Proof by Example: Frobenius Problem with $a_1 = 2$, $a_2 = 5$.



Why This Works:

The structure of integer points in an interval is easy.

What about the Frobenius problem with three generators?

Intervals become triangles.



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$$\begin{bmatrix} 3 & 4 & 5 \end{bmatrix} A = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}$$

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Columns of A form a basis for \mathbb{Z}^3 , so $A\mathbb{Z}^3 = \mathbb{Z}^3$. We will use A as a change of basis.

$$\Lambda = \left\{ \textbf{x} \in \mathbb{Z}^3: \begin{array}{cc} [3 \quad 4 \quad 5] \ \textbf{x} = 0 \right\}.$$

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Parametric Polytope: Normal vectors to facets determined by matrix whose columns are a basis for Λ . They stay the same, but the right-hand-sides vary.



Neighbors

Fix A. Let b vary.

Definition [Scarf]: $x, y \in \mathbb{Z}^d$ are neighbors if there exists a *b* such that the polytope

$$\{x: Ax \leq b\}$$

contains x and y but no other integer points.



Neighbors

We will assume genericity: there are no ties.



Should y_1 or y_2 be a neighbor of x?

This can be fixed with some sort of tie-breaking rule.

Neighbors

Examples: When A is a 3×2 matrix:



When A is a 2×1 matrix:



Neighbors are invariant under lattice translation.
Stepping among integer solutions to $Ax \le b$ in order to minimize $c \cdot x$.

Find neighbors with respect to the inequalities

$$\begin{bmatrix} \mathbf{A} \\ \mathbf{c} \end{bmatrix} \mathbf{x} \le \begin{bmatrix} \mathbf{b} \\ \mathbf{d} \end{bmatrix}$$

(*d* can be anything).

These are exactly the correct set of allowable steps [Scarf].



Given *x* feasible, is it optimal?



Given x feasible, is it optimal? If not:

- This region contains integer points other than x.
- Shrink until there is only one other such point y.
- Then y must be a neighbor of x. Step to y.



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There seems to be a 2-d complex hiding here.

Neighborhood Complexes

Define [Scarf] the following simplicial complex with vertices in \mathbb{Z}^d :

$$\{x_1, x_2, \cdots, x_k\} \subseteq \mathbb{Z}^d$$
 is a face
if and only if
there exists a *b* such that the polytope $\{x : Ax \leq b\}$ contains the
 x_i (on different facets), but no interior integer points.



This complex is invariant under lattice translations.

Neighborhood Complexes



Let $\Lambda = A\mathbb{Z}^d$, a sublattice of \mathbb{Z}^m . It is often convenient to look at the complex on these vertices.

What $b \in \mathbb{Z}^m$ defines the smallest polytope $\{Ax \leq b\}$ containing x_1, \ldots, x_k ?

It is the smallest b such that

 $Ax_i \leq b$ for all *i*.

We want

$$b = \operatorname{coord-max}(Ax_1, \ldots, Ax_k).$$

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 $\{x_1,\ldots,x_k\}\subseteq \mathbb{Z}^d$ is a face if and only if there is no $x\in \mathbb{Z}^d$ such that

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Example: A is a 3×2 matrix.



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Neighborhood complexes seems to be determined by an (m-1)-dimensional surface living naturally in \mathbb{R}^m .



It is awfully wrinkled.

We can iron this out.

A Geometric Realization Example: $A = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$.



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Let $Q \subseteq \mathbb{R}^m$ be the convex hull of

$$\mathbf{e}^{t\lambda}$$
: $\lambda \in \Lambda$,

for sufficiently large t.

The faces of Q are the faces of the neighborhood complex [Bárány, Howe, Scarf, Shallcross].



A Geometric Realization

Consequences:

- The neighborhood complex is contractible.
- ▶ The neighborhood complex is connected (this makes the "stepping" work in Teaser #1).
- The Euler characteristic

```
(\# vertices - \# edges + \#2-faces - \cdots)
```

is one.





coefficient of
$$t^s$$
 in $f(S; t) = \begin{cases} 1 & \text{if } s \in S \\ 0 & \text{if } s \notin S \end{cases}$
$$= \# \text{ vertices } - \# \text{ edges in complex} \end{cases}$$

$$f(S;t) = rac{1}{(1-t^2)(1-t^5)} - rac{t^{10}}{(1-t^2)(1-t^5)}.$$

- -

In general, let $M = \begin{bmatrix} a_1 & \cdots & a_n \end{bmatrix}$ be the matrix of generators of S.

Let A be an $n \times (n-1)$ matrix whose columns form a basis for $\Lambda = \{x \in \mathbb{Z}^n : Mx = 0\}.$

Compute the neighborhood complex, C, of A. C is lattice-invariant.

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For each face $F = (x_1, \ldots, x_k) \in \overline{C}$, let

$$\lambda_F^{max} = \operatorname{coord-max}(Ax_1, \ldots, Ax_k).$$

Then [Scarf, W]

$$f(S;t) = \frac{\sum_{F \in \overline{C}} (-1)^{\dim F} t^{M \lambda_F^{\max}}}{(1-t^{a_1}) \cdots (1-t^{a_n})}.$$

Example: For 3 generators, \overline{C} has 2 triangles, 3 edges, and 1 vertex.





So f(S; t) has 6 monomials in numerator.

Extensions:

 Also applies [Scarf, W; Bayer, Sturmfels] to higher dimensional semigroups. E.g., if S is generated by (1,3), (2,2), and (3,1)

$$f(S; s, t) = s^{0}t^{0} + s^{1}t^{3} + s^{2}t^{2} + s^{2}t^{6} + \cdots$$
$$= \frac{1 - s^{4}t^{4}}{(1 - s^{1}t^{3})(1 - s^{2}t^{2})(1 - s^{3}t^{1})}$$

Also applies [W] to any S = T(P ∩ Z^d), where P is a polytope and T is a projection. E.g., P = ℝ²_{≥0}, T(x,y) = 2x + 5y is Frobenius problem with generators 2 and 5.
Teaser #2, revisited

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Question: What is the largest integer that isn't in the semigroup generated by a_1, \ldots, a_n ?

Let p(t) be the numerator of f(S; t).

Let M = deg(p). *M* corresponds to the depth of the "deepest hole" in this picture.



Let
$$T = \mathbb{Z}_{\geq 0} \setminus S$$
.

$$f(T;t) = \frac{1}{1-t} - \frac{p(t)}{(1-t^{a_1})\cdots(1-t^{a_n})} \\ = \frac{(1-t^{a_1})\cdots(1-t^{a_n}) - (1-t)p(t)}{(1-t)(1-t^{a_1})\cdots(1-t^{a_n})}.$$

The largest integer not in S is the degree of the polynomial f(T; x), which is

$$(1+\deg(p))-(1+a_1+\cdots+a_n)=M-a_1-\cdots-a_n$$

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Neighbors of small matrices well understood:

- $m \times 1$ matrices: trivial (1 dimensional).
- 3×2 matrices [Scarf]: triangles tiling plane.
- ► m × 2 matrices [Scarf]: the set of neighbors of the origin lie in a small number of intervals.
- ► 4 × 3 matrices [Shallcross]: the set of neighbors lie in a small number of 2-d polytopes.
- ▶ Beyond? Unknown!! Lovász conjectured the set on neighbors lie in a small number of (d − 1)-dimensional polytopes.

Understanding the structure of neighborhood complexes would lead to algorithms for computing these generating functions.

The only known polynomial time (for fixed dimension) algorithm [Barvinok, W] fares poorly in practice:

- It takes a hammer to the geometry, but does it in polynomial time.
- Neighborhood complexes preserve the geometry beautifully, but don't have (known) polynomial-size structure.

A practical algorithm would need to treat the geometry more gently.

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Thank You!

