# Ideal Pendulum Handout \#2 <br> Math 427K <br> Jack Calcut 

This handout explores examples following the previous handout. Some solutions in this handout are numerical; you are required to understand the results.

The ODE governing the motion of the ideal pendulum is:

$$
\begin{equation*}
\theta^{\prime \prime}=-\frac{g}{L} \sin \theta \tag{1}
\end{equation*}
$$

We assume $\theta^{\prime}(0)=0$ and $-\pi<\theta(0) \leq \pi$. The two equilibrium solutions to (1) are:

$$
\begin{aligned}
& \theta_{0}(t)=0 \text { (hang straight down; stable), and } \\
& \theta_{\pi}(t)=\pi \text { (point straight up; unstable). }
\end{aligned}
$$

Throughout we fix $L=1 \mathrm{~m}$ and $g=+9.8 \mathrm{~m} / \mathrm{s}^{2}$. This corresponds roughly to a grandfather clock sized pendulum on the surface of the earth.

The linearization of our main ODE (1) is:

|  | Linearization | Solution |
| :---: | :---: | :---: |
| $\theta=0$ | $\theta^{\prime \prime}=-\frac{g}{L} \theta$ | $\theta(t)=\theta(0) \cos (t \sqrt{g / L})$ |
| $\theta=\pi$ | $\theta^{\prime \prime}=-\frac{g}{L}(-\theta+\pi)$ | $\theta(t)=[\theta(0)-\pi] \cosh (t \sqrt{g / L})+\pi$ |

Recall that the hyperbolic cosine is:

$$
\cosh x=\frac{e^{x}+e^{-x}}{2}
$$

Most often in basic physics one studies the linearized ODE at $\theta=0$ with solution $\theta(t)=$ $\theta(0) \cos (t \sqrt{g / L})$ where $\theta(0)$ is the amplitude and $2 \pi \sqrt{L / g}$ is the period. Note: in this case the period is independent of $m$ (mass of pendulum) and $\theta(0)$ (the initial displacement); if $\theta(0)=0$ we say the pendulum has any period (this is common convention).

Linearization at $\theta=0$ vs. Main ODE


Solutions $\theta(t)$ to linearization at $\theta=0$ for $\theta(0)=\pi / 6$ (thin), $\theta(0)=2 \pi / 6$ (medium), and $\theta(0)=3 \pi / 6$ (thick).


Solutions $\theta(t)$ to main $\operatorname{ODE}(1)$ for $\theta(0)=\pi / 6$ (thin), $\theta(0)=2 \pi / 6$ (medium), and $\theta(0)=3 \pi / 6$ (thick).

Exercise 1 Compare and contrast the two plots above. What are the main features to note? Recall the discussion of Galileo at the end of the previous handout.

## Bounds for Actual Period using Linearization

The second plot above shows that the actual period seems to increase as $\theta(0)$ increases in magnitude. Let us explore this further, first numerically:


Solutions $\theta(t)$ to main ODE (1) for $\theta(0)=3 \pi / 6$ (thin), $\theta(0)=4 \pi / 6$ (medium), $\theta(0)=5 \pi / 6$ (thick), $\theta(0)=11 \pi / 12$ (thindot), and $\theta(0)=23 \pi / 24$ (mediumdot).

The actual period continues to increase as $\theta(0)$ increases to $\pi$.
Our goal is to obtain bounds for the actual period when $\theta(0)$ is close to $\pi$.
Instead, let us bound the time it takes for the pendulum to fall from $\pi / 2<\theta(0)<\pi$ to $\pi / 2 \mathrm{rad}$.

## Lower Bound via Linearization at $\theta=\pi$

This linearization:

$$
\theta^{\prime \prime}=-\frac{g}{L}(-\theta+\pi)
$$

was obtained by replacing $\sin \theta$ with $-\theta+\pi$ in our $\operatorname{ODE}(1)$ :

$$
\theta^{\prime \prime}=-\frac{g}{L} \sin \theta
$$

Note that $|\sin \theta| \leq|-\theta+\pi|$ for ALL $\theta$, with equality only for $\theta=\pi$. Thus, by linearizing we have INCREASED the magnitude of acceleration of our pendulum. This means we have only DECREASED the time it takes to fall to $\pi / 2$ (so we obtain a lower bound on the time).

The solution to our linearized ODE is:

$$
\theta(t)=[\theta(0)-\pi] \cosh (t \sqrt{g / L})+\pi .
$$

Thus, we solve $\theta(t)=\pi / 2$ for $t$ (as a function of $\theta(0)$ ):

$$
\begin{aligned}
\pi / 2 & =\theta(t)=[\theta(0)-\pi] \cosh (t \sqrt{g / L})+\pi \\
-\pi / 2 & =[\theta(0)-\pi] \cosh (t \sqrt{g / L}) \\
\frac{\pi}{2[\pi-\theta(0)]} & =\cosh (t \sqrt{g / L}) \\
t \sqrt{g / L} & =\cosh ^{-1}\left(\frac{\pi}{2[\pi-\theta(0)]}\right) \\
t & =\sqrt{L / g} \cosh ^{-1}\left(\frac{\pi}{2[\pi-\theta(0)]}\right)
\end{aligned}
$$

Recall that:

$$
\cosh ^{-1}(x)=\ln \left(x+\sqrt{x^{2}-1}\right) \text { for } x \geq 1
$$

Exercise 2 Verify that the use of $\cosh ^{-1}$ above is in the valid domain.
In this handout $L=1$ and $g=9.8$. So we obtain:

$$
t=1 / \sqrt{9.8} \cosh ^{-1}\left(\frac{\pi}{2[\pi-\theta(0)]}\right)
$$

as a lower bound for the time it takes the pendulum to fall from $\theta(0)$ to $\pi / 2$. We plot $t$ as a function of $\theta(0)$ :


Exercise 3 Show that this lower bound for $t$ approaches $\infty$ as $\theta(0) \rightarrow \pi^{-}$.
Exercise 4 What does the previous exercise imply?

Let us compare this lower bound for time to fall from $\theta(0)$ to $\pi / 2$ with the actual time (in s ):

| $\theta(0)$ | Lower Bound | Actual Time |
| :---: | :---: | :---: |
| $3 \pi / 6$ | 0.000 | 0.000 |
| $4 \pi / 6$ | 0.307 | 0.344 |
| $5 \pi / 6$ | 0.563 | 0.590 |
| $11 \pi / 12$ | 0.792 | 0.811 |
| $23 \pi / 24$ | 1.015 | 1.033 |

## Upper Bound

Exercise 5 Obtain a useful upper bound for the time to fall from $\theta$ (0) to $\pi / 2$.
Hint: replace $\sin \theta$ in (1) with a linear function of $\theta$ that DECREASES the magnitude of acceleration.

